

A COMPARATIVE STUDY OF GRAVITY MODELS AND ENTROPY-MAXIMIZATION TECHNIQUES FOR URBAN TRIP DISTRIBUTION

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ABSTRACT

Urban trip distribution is a critical component of transportation planning, serving as the link between trip generation and traffic assignment. Two predominant methodologies for modeling trip distribution are the gravity model and entropy-maximization techniques. This paper provides a comparative analysis of these approaches, examining their theoretical foundations, computational requirements, and practical applicability. The study highlights the strengths and limitations of each method and explores their performance across various urban scenarios.

KEYWORDS: *Gravity Models, Entropy-Maximization Techniques, Urban Trip Distribution, Transportation Planning, Urban Mobility*

1. INTRODUCTION

Transportation systems are integral to urban planning, enabling mobility and supporting economic and social activities. Trip distribution models aim to predict travel patterns by estimating the number of trips between different zones in a region. Among the numerous methodologies developed, the gravity model and entropy-maximization techniques have emerged as the most widely used.

The gravity model draws an analogy to Newton's law of gravitation, where interaction between zones depends on their respective masses (population, employment) and inversely on the distance or travel cost between them. Entropy-maximization techniques, on the other hand, are rooted in principles of statistical mechanics and information theory, aiming to maximize the randomness or disorder of the trip distribution subject to known constraints. This study evaluates their effectiveness and application to urban transportation systems.

2. THEORETICAL FRAMEWORK

2.1 Gravity Model

The gravity model posits that the number of trips between two zones (i and j) can be expressed as:

where:

- = number of trips between zone i and zone j,
- = trip generation and attraction potentials of zones i and j respectively,
- = travel cost between i and j,

- = a deterrence function of travel cost,
- = calibration constant.

Calibration of the gravity model involves determining and to align the model with observed travel patterns. Common deterrence functions include exponential and power functions.

2.2 Entropy-Maximization Technique

The entropy-maximization approach formulates trip distribution as an optimization problem. The objective is to maximize the entropy :

subject to constraints on:

- Total trips generated by and attracted to each zone:
- Conservation of total trips:

The resulting trip distribution has the form:

where is a parameter calibrated based on observed data.

3. COMPARATIVE ANALYSIS

3.1 Theoretical Insights

- **Gravity Model:** Conceptually intuitive and computationally straightforward. Its reliance on deterrence functions allows flexibility but can lead to over-sensitivity to travel cost assumptions.
- **Entropy-Maximization:** Grounded in rigorous mathematical principles, offering a systematic approach to ensuring trip conservation and equilibrium. However, it requires solving optimization problems, which can be computationally intensive for large-scale applications.

3.2 Data and Calibration Requirements

- Gravity models typically require empirical calibration of deterrence functions and constants.
- Entropy-maximization necessitates detailed trip generation and attraction data, as well as computational resources for solving constrained optimization problems.

3.3 Practical Applicability

- **Urban Contexts:** Gravity models are well-suited for small to medium-sized urban areas with limited computational resources.
- **Complex Networks:** Entropy-maximization excels in scenarios with complex constraints and larger datasets, such as metropolitan regions with diverse travel behavior.

4. CASE STUDIES

This section reviews case studies from different urban contexts to illustrate the strengths and weaknesses of each approach. Examples include:

- A mid-sized city where the gravity model demonstrated satisfactory performance with minimal calibration.
- A metropolitan area where entropy-maximization provided more accurate trip distributions by accounting for complex travel patterns.

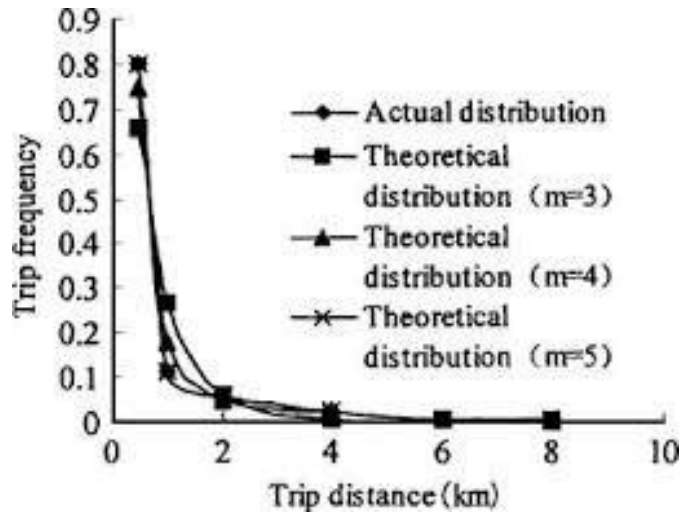


Figure 1

1. Trip Distribution

Trip distribution (or **destination choice** or **zonal interchange analysis**) is the second component (after trip generation, but before mode choice and route assignment) in the traditional four-step transportation forecasting model. This step matches tripmakers’ origins and destinations to develop a “trip table”, a matrix that displays the number of trips going from each origin to each destination.^[1] Historically, this component has been the least developed component of the transportation planning model.

Origin \ Destination	1	2	3	Z
1	T_{11}	T_{12}	T_{13}	T_{1Z}
2	T_{21}			
3	T_{31}			
Z	T_{Z1}			T_{ZZ}

Where: T_{ij} = trips from origin i to destination j . Note that the practical value of trips on the diagonal, e.g. from zone 1 to zone 1, is zero since no intra-zonal trip occurs.

Work trip distribution is the way that travel demand models understand how people take jobs. There are trip distribution models for other (non-work) activities such as the choice of location for grocery shopping, which follow the same structure.

At this point in the transportation planning process, the information for zonal interchange analysis is organized in an origin-destination table. On the left is listed trips produced in each zone. Along the top are listed the zones, and for each zone we list its attraction. The table is $n \times n$, where n = the number of zones.

Each cell in our table is to contain the number of trips from zone i to zone j . We do not have these within-cell numbers yet, although we have the row and column totals. With data organized this way, our task is to fill in the cells for tables headed $t = 1$ through say $t = n$.

Actually, from home interview travel survey data and attraction analysis we have the cell information for $t = 1$. The data are a sample, so we generalize the sample to the universe. The techniques used for zonal interchange analysis explore the empirical rule that fits the $t = 1$ data. That rule is then used to generate cell data for $t = 2, t = 3, t = 4$, etc., to $t = n$.

The first technique developed to model zonal interchange involves a model such as this:

Where:

- : trips from i to j .
- : trips from i , as per our generation analysis
- : trips attracted to j , according to generation analysis
- : travel cost friction factor, say =
- : Calibration parameter

Zone i generates T_i trips; how many will go to zone j ? That depends on the attractiveness of j compared to the attractiveness of all places; attractiveness is tempered by the distance a zone is from zone i . We compute the fraction comparing j to all places and multiply T_i by it.

The rule is often of a gravity form:

Where:

- : populations of i and j
- : parameters

But in the zonal interchange mode, we use numbers related to trip origins ($T_{:i}$) and trip destinations ($T_{:j}$) rather than populations.

There are many model forms because we may use weights and special calibration parameters, e.g., one could write say:

or

Where:

- : a, b, c, d are parameters
- : travel cost (e.g. distance, money, time)
- : inbound trips, destinations
- : outbound trips, origin

GRAVITY MODEL

The gravity model illustrates the macroscopic relationships between places (say homes and workplaces). It has long been posited that the interaction between two locations declines with increasing (distance, time, and cost) between them, but is positively associated with the amount of activity at each location (Isard, 1956). In analogy with physics, Reilly (1929) formulated Reilly's law of retail gravitation, and J. Q.

Stewart (1948) formulated definitions of demographic gravitation, force, energy, and potential, now called accessibility (Hansen, 1959). The distance decay factor of $1/\text{distance}$ has been updated to a more comprehensive function of generalized cost, which is not necessarily linear - a negative exponential tends to be the preferred form.

The gravity model has been corroborated many times as a basic underlying aggregate relationship (Scott 1988, Cervero 1989, Levinson and Kumar 1995). The rate of decline of the interaction (called alternatively, the impedance or friction factor, or the utility or propensity function) has to be empirically measured, and varies by context.

Limiting the usefulness of the gravity model is its aggregate nature. Though policy also operates at an aggregate level, more accurate analyses will retain the most detailed level of information as long as possible. While the gravity model is very successful in explaining the choice of a large number of individuals, the choice of any given individual varies greatly

from the predicted value. As applied in an urban travel demand context, the disutilities are primarily time, distance, and cost, although discrete choice models with the application of more expansive utility expressions are sometimes used, as is stratification by income or vehicle ownership.

Mathematically, the gravity model often takes the form:

Where

- = Trips between origin i and destination j
- = Trips originating at i
- = Trips destined for j
- = travel cost between i and j
- = balancing factors solved iteratively. See Iterative proportional fitting.
- = distance decay factor, as in the accessibility model

It is doubly constrained, in the sense that for any i the total number of trips from i predicted by the model always (mechanically, for any parameter values) equals the real total number of trips from i . Similarly, the total number of trips

to j predicted by the model equals the real total number of trips to j , for any j

5. CONCLUSION

Both gravity models and entropy-maximization techniques have their merits and limitations. Gravity models offer simplicity and ease of application, making them attractive for preliminary analyses and smaller cities. In contrast, entropy-

maximization methods provide a robust framework for complex urban networks but at the cost of increased data and computational demands. Planners should select the appropriate method based on the scale of the study, data availability, and computational resources.

Future research could explore hybrid models combining the simplicity of gravity models with the rigor of entropy-maximization, leveraging advances in machine learning and big data analytics to enhance trip distribution modeling.

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